EE515 Security of Emerging Systems

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Admin

- Find your group members and discuss about projects
- □ Project pre-proposal deadline: 9/29/2024



Security of New Technologies

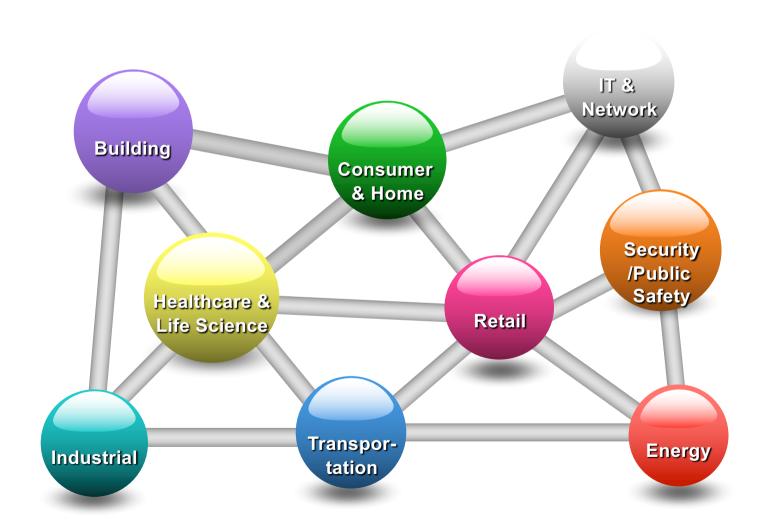
- Most of the new technologies come with new and old vulnerabilities.
 - Old vulnerabilities: OS, Network, Software Security,
 - Studying old vulnerabilities is important, yet less interesting.
 - e.g. Stealing Bitcoin wallet, Drone telematics channel snooping
- New Problems in New Technologies
 - Sensors in Self-Driving Cars and Drones
 - Security of Deep Learning
 - Block Chain Pool Mining Attacks
 - Brain Hacking



Old Vulnerabilities in New Techs

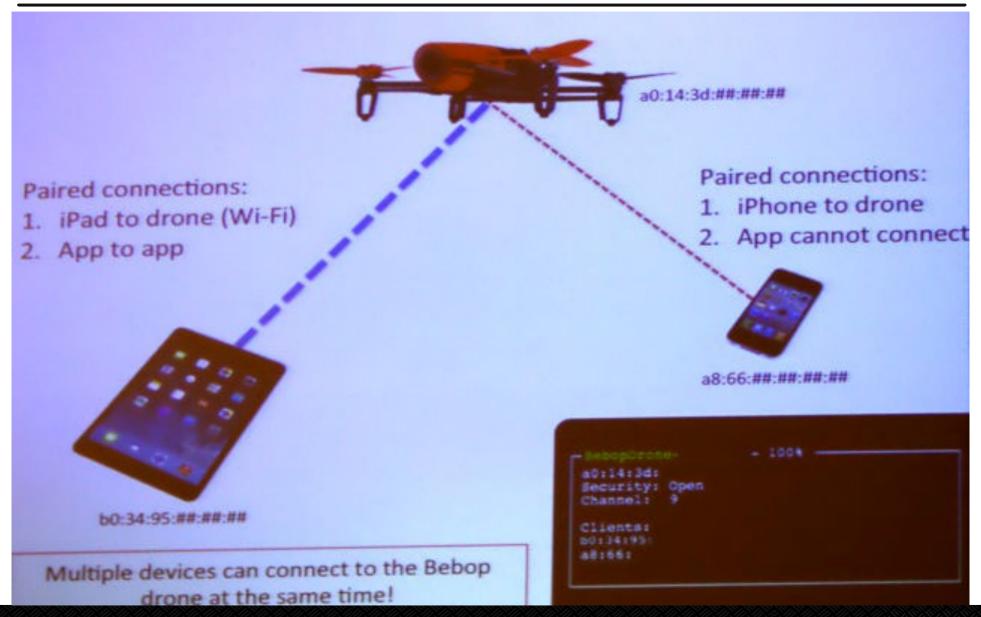


IoT and Security

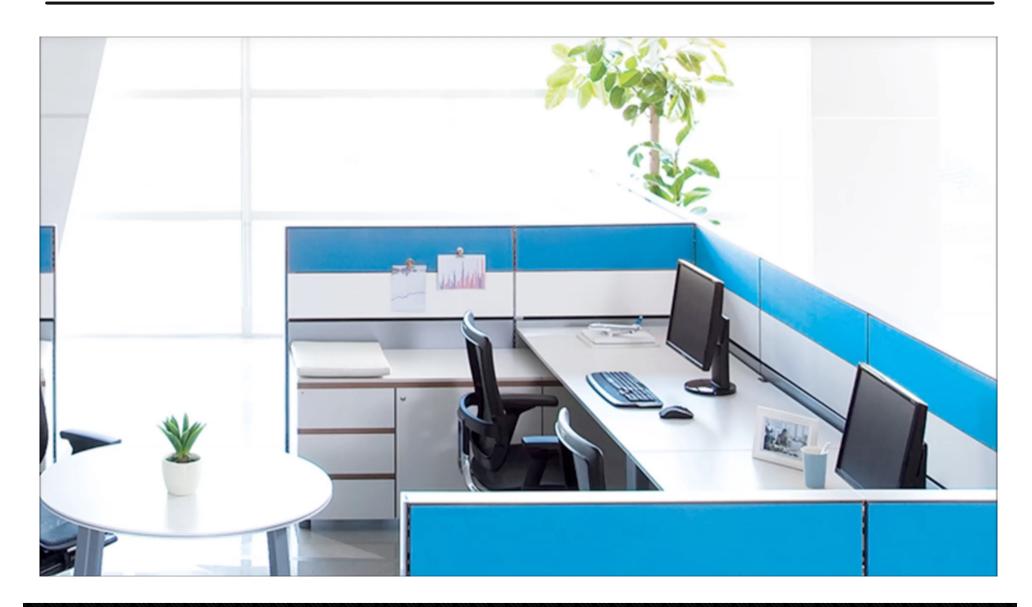




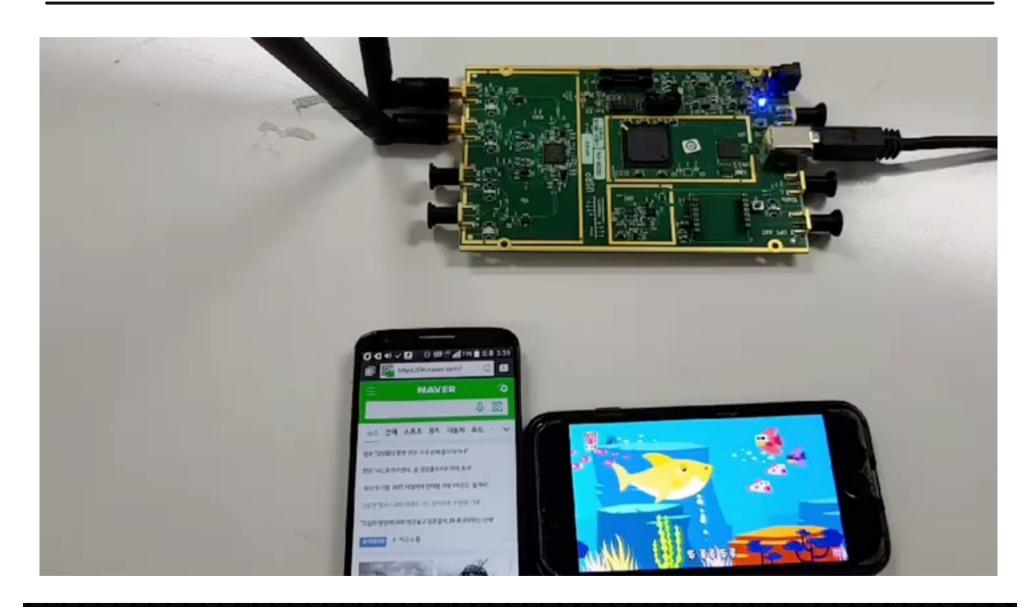
Drone Hacking



Eavesdropping Phone Calls



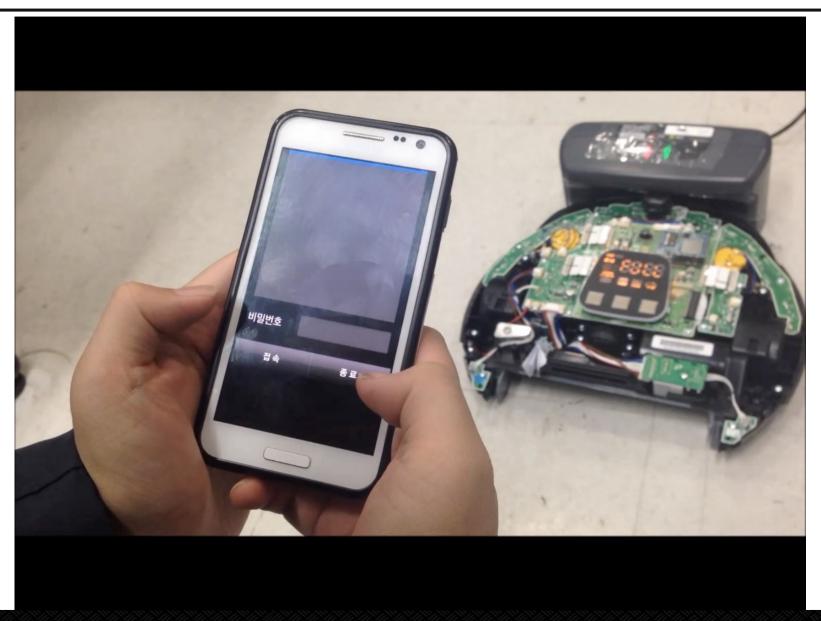
Emergency SMS



Digital Doorlock



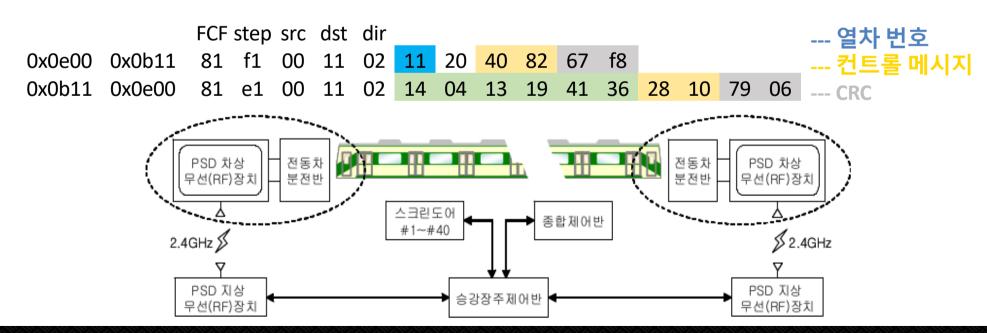
로봇청소기





Seoul Subway Screen Door

- □ IEEE 802.15.4 + ZigBee based RF control
- No encryption

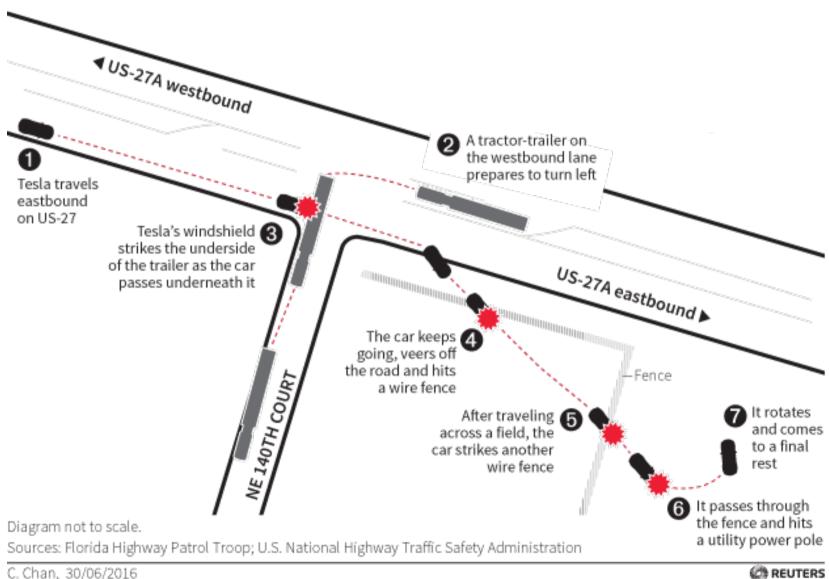


코레일

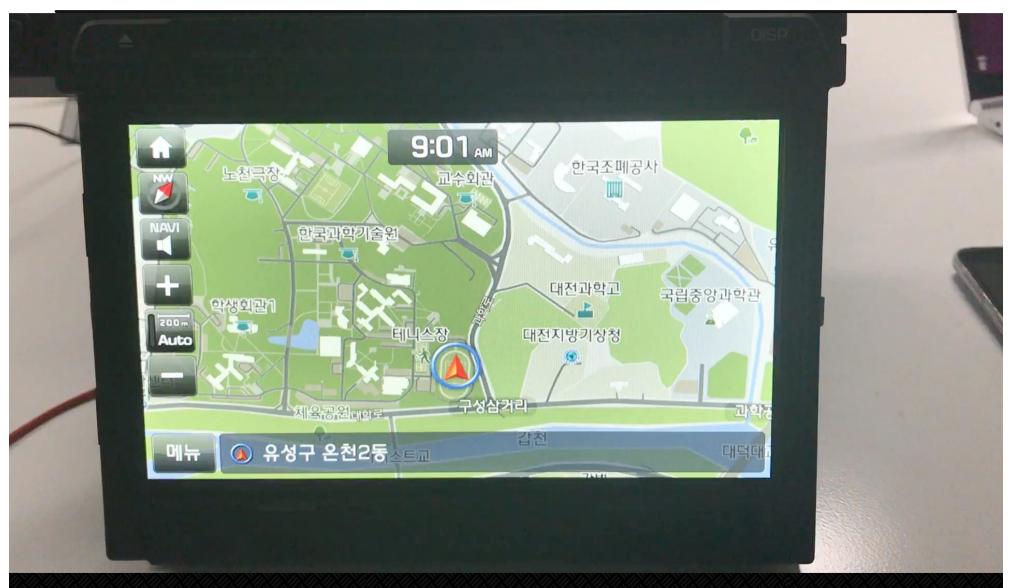
코레일 인포메이션 관리부실 원격체어 접근성공 스케쥴러 제거 보안 툴 암호 없음 카카오스토리 Vellocatus 지켜보고 있습니다. 코레일

New vulnerabilities in New Techs

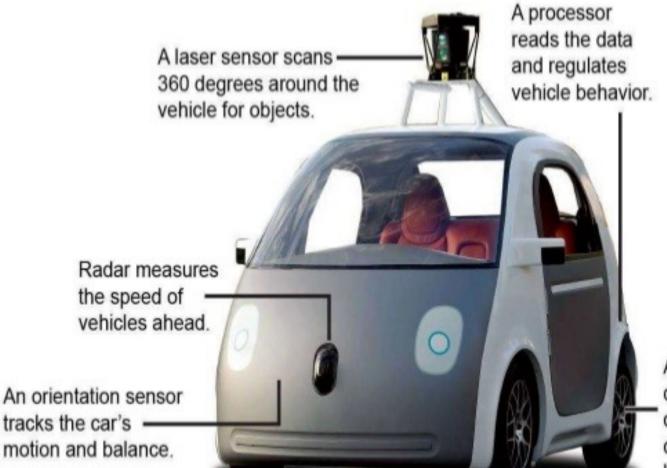




Result (DEMO)



TECHNOLOGIES



A wheel-hub sensor detects the number of rotations to help determine the car's location.

Mobileye Mobileye



- **GM**
- BMW
- Nissan
- Volvo
- (over 19 in total)



Mobileye-560 [Unpublished]

- Classify the objects
 - Vehicle, Pedestrian, Truck, Bike,
 Bicycle, Sign, Lane etc.
- Information about the Object
 - Distance, Velocity, State, etc.
- **❖** Recognition range : ∼80m
- **❖** Black and White screen





Parser

Parser prints the results for black box video.

(Object classification, velocity, accelerometer ...)



```
C:\Users\SysSec-EE\Desktop\CAN Receive\\Debug\CAN Receive.exe
Num_Obstacles : 2
STOP!!!
Existing object
Obstacle is Vehicle
Obstacle parked
              X: 16.625 m,
                               Y: −1.938 m
Obstacle
Obstacle vel X: -0.000
Obstacle length: 31,500 m, width: 1,450 m
Obstacle age: 254
Obstacle lane not assigned
Obstacle angle rate: -0.210 deg/sec, scale change: 0.001 pix/sec
Obstacle acc: -0.480 m/s2
Obstacle angle: -321.020 deg
Existing object
Obstacle is Bike
Obstacle is standing
                                Y: 2.930 m
              X: 47.313 m,
Obstacle
Obstacle vel_X: -0.000
Obstacle length: 31.500 m, width: 0.600 m
Obstacle age: 254
Obstacle lane not assigned
Obstacle angle rate: 0.110 deg/sec, scale change: -0.003 pix/sec
```



Camera module blinded by laser injection

Mobileye Classification



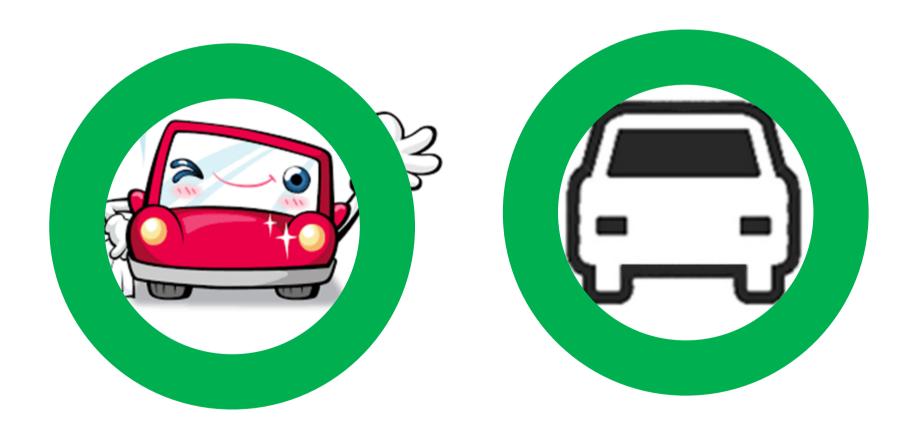






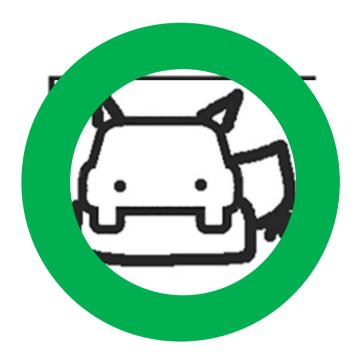


Are You Serious?



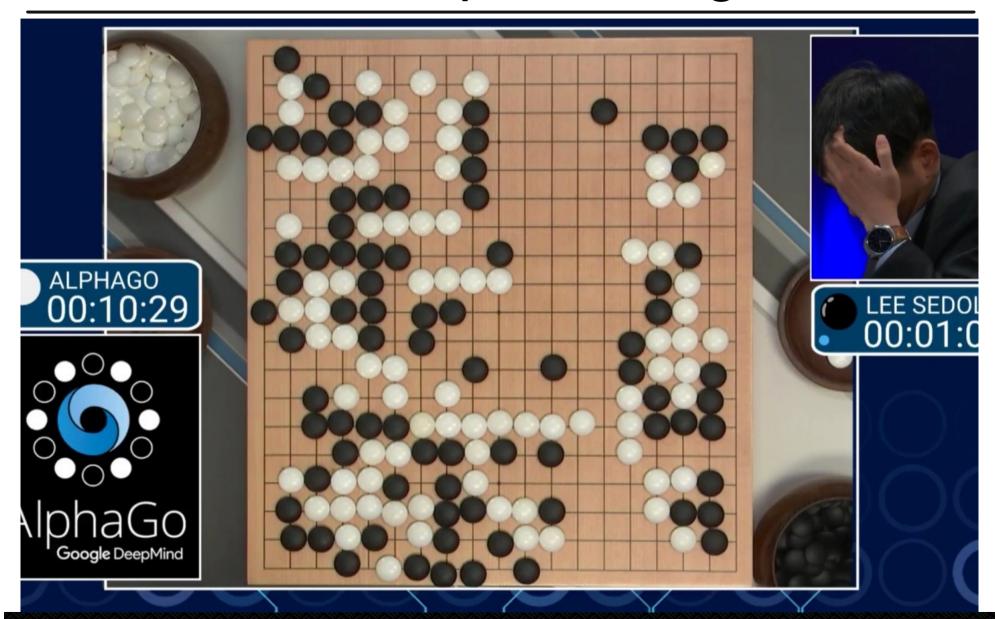


Variations





AI, Deep Learning







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Questions?

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